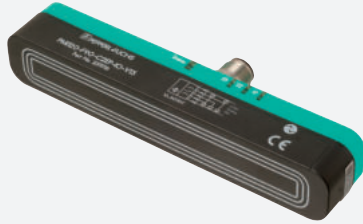


Inductive positioning system

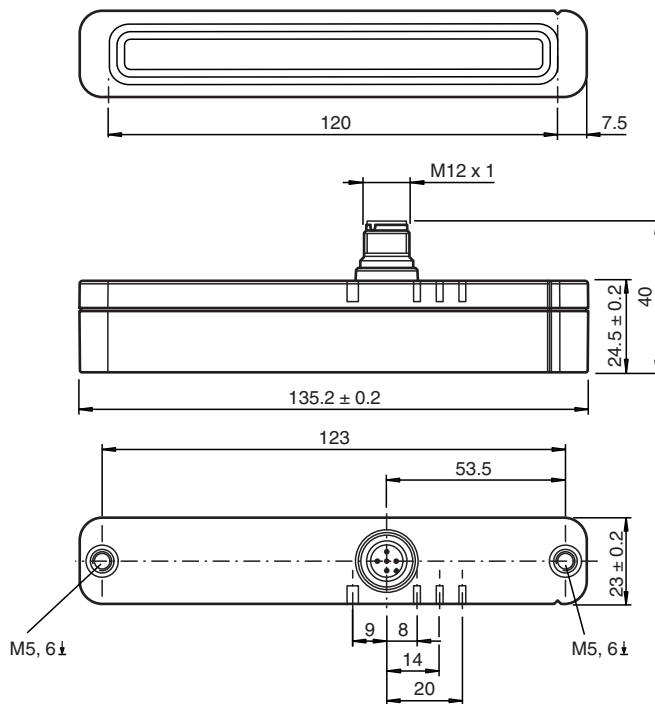
PMI120-F90-3EP-IO-V15



- Parameterization and diagnosis via IO-Link
- Measuring range 0 ... 120 mm
- Parameterisable measuring range
- 3 Push-pull outputs
- Switch points programmable via IO-Link



Dimensions



Technical Data

General specifications

Switching element function	3 switch outputs, programmable
Object distance	0.5 ... 3 mm , recommended: 1.5 mm
Measurement range	0 ... 120 mm
Linearity range	1 ... 119 mm

Nominal ratings

Operating voltage	U_B	12 ... 30 V DC
Reverse polarity protection		reverse polarity protected
Linearity error		within measuring range: ± 0.8 mm within linearity range: ± 0.4 mm

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Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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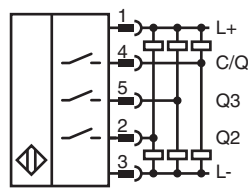
PEPPERL+FUCHS

Technical Data

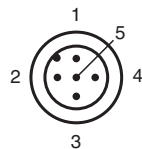
Repeat accuracy	R	± 0.1 mm
Resolution		50 µm
Temperature drift		± 0.5 mm (-25 °C ... 70 °C)
No-load supply current	I ₀	≤ 40 mA
Operating voltage indicator		LED green
Functional safety related parameters		
MTTF _d		271 a
Mission Time (T _M)		20 a
Diagnostic Coverage (DC)		0 %
Indicators/operating means		
LED S1		switching state Switching output 1
LED S2		switching state Switching output 2
LED S3		switching state, Switching output 3
LED STATUS		Status display LED, green/red (Power on, communication/error, missing damping element)
Interface		
Interface type		IO-Link (via C/Q = Pin 4)
IO-Link revision		1.1
Device profile		Smart Sensor
Device ID		0x200402 (2098178)
Transfer rate		COM2 (38.4 kBaud)
Value range		0000h ... 9600h
Min. cycle time		2.3 ms
Process data width		Process data input: 16 Bit Process data output: none
SIO mode support		yes
Compatible master port type		A
Switching output		
Output type		3 push-pull outputs (can be parameterized), short-circuit-proof, reverse polarity protection, overvoltage protected
Operating current	I _L	≤ 100 mA / Output
Switching window		± 1 mm
Switching hysteresis		0.2 mm
Voltage drop		≤ 3 V
Short-circuit protection		pulsing
Compliance with standards and directives		
Standard conformity		
Standards		EN 60947-5-2:2007 EN 60947-5-2/A1:2012 IEC 60947-5-2:2007 IEC 60947-5-2 AMD 1:2012 IEC 61131-9:2013 EN 61131-9:2013
Approvals and certificates		
UL approval		cULus Listed, Class 2 Power Source, Type 1 enclosure
Marine approval		DNVGL TAA00001V2
Ambient conditions		
Ambient temperature		-25 ... 85 °C (-13 ... 185 °F)
Mechanical specifications		
Connection type		5-pin, M12 x 1 connector
Degree of protection		IP67 / IP69K
Material		
Housing		PBT, stainless steel 1.4571, brass, nickel-plated
Target		mild steel, e. g. 1.0037, SR235JR (formerly St37-2)
Mass		113 g

Release date: 2022-05-17 Date of issue: 2022-05-17 Filename: 231922_eng.pdf

Connection



Connection Assignment

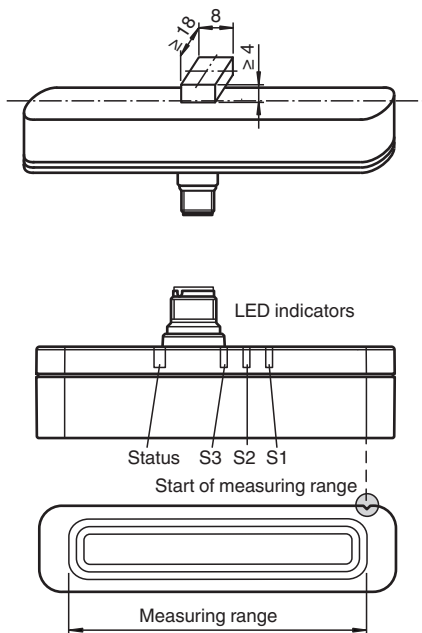


Wire colors in accordance with EN 60947-5-2

1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)
5	GY	(gray)

Application

dimensions for the target object:



Accessories

	BT-F90-W	Damping element for sensors of type F90, F112, and F166; side hole
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Accessories

	MH-F90	Mounting bracket for mounting of F90 sensors
	V15-G-2M-PVC	Female cordset single-ended M12 straight A-coded, 5-pin, PVC cable grey
	V15-W-2M-PVC	Female cordset single-ended M12 angled A-coded, 5-pin, PVC cable grey
	ICE2-8IOL-G65L-V1D	EtherNet/IP IO-Link master with 8 inputs/outputs
	ICE3-8IOL-G65L-V1D	PROFINET IO IO-Link master with 8 inputs/outputs
	ICE1-8IOL-G30L-V1D	Ethernet IO-Link module with 8 inputs/outputs
	ICE1-8IOL-G60L-V1D	Ethernet IO-Link module with 8 inputs/outputs
	ICE2-8IOL-K45P-RJ45	EtherNet/IP IO-Link master with 8 inputs/outputs, DIN rail, push-in connectors
	ICE2-8IOL-K45S-RJ45	EtherNet/IP IO-Link master with 8 inputs/outputs, DIN rail, screw terminal
	ICE3-8IOL-K45P-RJ45	PROFINET IO IO-Link master with 8 inputs/outputs, DIN rail, push-in terminals
	ICE3-8IOL-K45S-RJ45	PROFINET IO IO-Link master with 8 inputs/outputs, DIN rail, screw terminal
	IO-Link-Master02-USB	IO-Link master, supply via USB port or separate power supply, LED indicators, M12 plug for sensor connection

Operation

Attention!

If the sensor is supplied via an IO-Link-Master, ensure that the sum of the no-load supply current and operating currents of all sensor outputs does not exceed the maximum current the IO-Link-Master can supply.